A Guide to the Use of Left Ventricular Analysis with 3D Echo in Dyssynchrony

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Abstract
Data from single-centre studies suggest that echocardiographic parameters of mechanical dyssynchrony may improve patient selection for cardiac resynchronisation therapy (CRT). To our knowledge, the only published multicentre trial that compared 12 echocardiographic methods, the Predictors of response to cardiac resynchronization therapy (PROSPECT) trial, stated that none of the echocardiographic measurements of ventricular dyssynchrony applied in the study were able to distinguish responders from non-responders. Realtime 3D echocardiography is able to measure left ventricular (LV) size, function and dyssynchrony to identify the presence and extension of scar tissue and to evaluate where the site of latest mechanical activation is. After CRT device implantation, it also allows physicians to detect where the first mechanical activation secondary to LV pacing is located. Indeed, it can be useful in interventricular (VV) delay optimisation of the device after the implantation and, in single-centre studies, it was able to predict response to CRT and to identify responders from non-responders. Care must be taken to optimise temporal resolution, but now volume rates of 70–80vps can be easily obtained in the majority of cases. VV optimisation using realtime 3D echocardiography is feasible and intuitive, but time-consuming compared with traditional methods based on Doppler or algorithms. In this article we illustrate our approach to LV analysis with realtime 3D echocardiography in the study of dyssynchrony.

Keywords
Volume echocardiography, realtime 3D echocardiography, left ventricular (LV) analysis, dyssynchrony, response to cardiac resynchronisation therapy (CRT), interventricular (VV) optimisation

Disclosure: The authors have no conflicts of interest to declare.
Received: 11 February 2011 Accepted: 12 March 2011 Citation: European Cardiology, 2011;7(2):84-8
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Support: The publication of this article was supported by Siemens Healthcare.

3D Echocardiography – Advantages and Limits
Even the authors of the PROSPECT trial stated that, among the echocardiographic methods under investigation, strain measurements,
The advantages of realtime 3D echocardiography in this setting are clear and are confirmed also by the American Society of Echocardiography (ASE) Consensus Statement 14 by the assumption that LV dyssynchrony in reality is a 3D phenomenon. Nevertheless, disadvantages are pointed out that primarily include a lower spatial and temporal resolution, with frame rates for 3D wide-sector image acquisition at 20 to 30 frames/second with gated acquisition15,16 and even lower in some studies with single-beat acquisition. In the study of dyssynchrony, the temporal resolution is critical, and Doppler methods work with frame rates of more than 100fps. Using a frame rate of 20 or 30fps could lead to an unreliable assessment of mechanical activation of the various segments. But even with this limit, Kapetanakis and colleagues15 and Ajmone Marsan and colleagues16 showed good results in the study of dyssynchrony with realtime 3D echocardiography.

The first paper about the use of realtime 3D echocardiography in quantification of global LV mechanical dyssynchrony was by Kapetanakis and colleagues. A new index named the Systolic Dyssynchrony Index (SDI) was devised: by calculating the time taken by any segment to reach minimum regional, SDI was defined as the standard deviation of all these intervals; it was expressed as a percentage of the duration of the cardiac cycle rather than in milliseconds in order to allow comparison between patients with different heart rates.15

Using SDI, Ajmone Marsan and colleagues16 were able to predict responders from non-responders performing realtime 3D echocardiography before and 48 hours after CRT device implantation. Receiver operating characteristic (ROC) curve analysis revealed that a cut-off value for SDI of 5.6% yielded a sensitivity of 88% with a specificity of 86% to predict acute echocardiographic response to CRT. Moreover, identifying as responders patients with an acute reduction of >15% of LV end-systolic volume, reflecting acute improvement in LV systolic function, they found that basal SDI in the non-responders group was normal – acute non-responders to CRT did not have mechanical dyssynchrony.

More recently, Lau and colleagues17 performed realtime 3D echocardiography before implantation of the CRT pacemaker, 24 hours after implantation and six to 12 months after implantation. Using the same cut-off in reduction of LV end-systolic volume to identify responders from non-responders, they found that all responders had baseline SDI values of >10, with a negative predictive value of 100% and in these patients a decrease in the SDI value of more than five at 24 hours identified responders with a positive predictive value of 83%. These papers show that, besides variability of SDI cut-off, realtime 3D echocardiography seems to have good sensitivity and specificity in the prediction of acute response to CRT.

Realtime 3D Echocardiography in the Evaluation of Dyssynchrony – How to Perform the Exam

We suggest performing 3D echocardiography after a conventional 2D examination. It is necessary to use 3D echocardiography because spatial and time resolution are superior to realtime 3D echocardiography (RT3DE) in visualisation of dyskinetic areas and thickness of myocardial segments, and therefore in the evaluation of presence and extension of scar tissue.

**Figure 1: Volumetric Image of the Left Ventricle and Time Volume Curves with a Frame Rate of 80vps**

- In the upper panel (A) a volumetric image of the LV is shown. Spatial resolution is not good because ‘T2’ preset and fundamental imaging have been chosen, but the endocardial border in 2D views on the left is well recognisable. With this setting, a reduced width of the window and depth just below the mitral valve a frame rate of 80fps is obtained, thus allowing a nice analysis of dyssynchrony, as curves in panel B show (focus on the multitude of points on a single-beat analysis. LV = left ventricle.)
Imaging

Figure 2: Contraction Front Mapping and Time Volume Curves Before and After Cardiac Resynchronisation Therapy Device Implantation

A: contraction front mapping (CFM) before cardiac resynchronisation therapy (CRT) device implantation shows a delay in septal wall, which disappears after implantation of the device (C). Basal curves in panel B show severe dysynchrony that is due to the scar; in fact, it disappears if scar segments are excluded from the analysis (D). In panel C, the first point that reaches the minimum volume is shown by the blue arrow; this represents the position of left ventricular (LV) lead inside the scar.

When acquiring volume for LV analysis, great care must be taken to optimise time resolution. Some instruments allow you to choose between a good spatial and temporal resolution, for example the Siemens ACUSON SC2000™ ultrasound system allows you to choose between S2 (best spatial resolution), S1, T1 and T2 (best temporal resolution). Our suggestion is to look at 2D four- and two-chamber reconstruction more than the 3D volumetric image. If the endocardial border is clearly visualised in 2D images, LV analysis can even be performed in the presence of a suboptimal 3D image, as clearly shown in Figure 1. Time resolution can also be increased by working in fundamental imaging (without harmonic), reducing depth just below the mitral valve (visualisation of the left atrium is not necessary for LV analysis) and reducing the width of the volumetric data set. It must be ensured that all LV cavity is inside the volume; this can be easily provided looking at 2D reference planes extracted from the volume data set. These techniques can lead to a frame rate (or better, volume rate, dealing with a 3D image) of 70–80 volumes per second if the LV is not severely dilated (see Figure 1).

It is recommended to optimise brightness and contrast in order to improve the definition of the endocardial border and to check if the system has recognised the end diastolic frame and the end systolic frame properly. If a CRT device has been implanted, the system could recognise the spike as the end diastolic frame and you will have to correct it. The reliability of automated border detection is crucial. If the system does not properly recognise the endocardial border in four-, two- and three-chamber view and you have to correct it extensively, it will be unlikely to perform a nice LV analysis. Unfortunately, if the quality is low you cannot improve it with contrast, as automated border detection does not recognise contrast and is not able to recognise the endocardial border if the cavity is white and the muscle is dark. When LV analysis is complete, the system gives information about LV volumes and function (EF, stroke volume, sphericity index) and dysynchrony (SDV with a 16-segments model and with a 17-segments model).

Time volume curves of all segments are visualised with absolute and normalised values. In the first modality you can have information about kinesis of each segment, eventually confirming the presence and the extension of a scar, while the second modality shows when each segment reaches the minimum volume – that gives an idea of dysynchrony and detects which is the most delayed segment (see Figure 1).

Eventually, a bull’s eye with contraction front mapping (CFM) can be shown visualising time to minimum volume (see Figure 2). This is a very intuitive way to show the contraction wavefront propagation and may suggest the best position to implant LV lead. In fact, the region of latest activation is not always in the posterolateral wall and positioning of the LV lead guided by the latest activated area may help in achieving CRT response, although conditioned by anatomical limitations. If the lead is positioned away from the region of latest activation it is likely that response to CRT would be poorer, especially if the lead is placed in a segment with scar tissue. CFM is a good and easy method also to identify, after implantation of the CRT device, where the first mechanical activation due to LV pacing is located and how the LV pacing modifies the contraction wavefront propagation map (see Figure 3).

The Use of Realtime 3D Echocardiography in Pacemaker Optimisation

After CRT device implantation, the pacemaker programming can be optimised in order to achieve the optimal resynchronisation and improve the outcome. Usefulness of optimisation of atrioventricular (AV) and interventricular (VV) delays is debated. Trials that compared various method of optimisation are controversial and at this time routine use of optimisation techniques is not warranted.
Dyssynchrony can occur at three levels (AV, inter- and intraventricular), but a meta-analysis on 24 studies by J Bax and J Gorcsan\(^1\) showed that intra-LV dyssynchrony is much more important than AV and VV dyssynchrony in evaluating the response to CRT. In AV optimisation, realtime 3D echocardiography is not useful and algorithms or methods based on mitral Doppler can be used. On the contrary, intra-LV dyssynchrony can be minimised by optimisation of VV delay using CFM as a guide. We suggest to start with a LV delay of zero milliseconds and perform an LV analysis and subsequently repeat it at LV +20 milliseconds and LV -20 milliseconds. LV systolic function, by means of EF and LV dyssynchrony, by means of SDI, can be analysed and compared between the three programs: so far we suggest to choose the best compromise between the best function and the least dyssynchrony. CFM, showing contraction wavefront propagation map and the region of maximum delay, will guide further steps in optimisation: if, for example, posterolateral segment is still delayed at LV -20 milliseconds, LV stimulus can be further anticipated at -40 milliseconds and LV analysis repeated to see how CFM, EF and SDI behave (see Figure 4). Obviously, this technique, requiring three or four LV volume analysis, is more time-consuming than the traditional methods in this setting.

Figure 4: Utility of Realtime 3D Echo in Interventricular Optimisation

![Utility of realtime 3D echocardiography in interventricular (VV) optimisation. In upper panel (A) analysis with synchronous left ventricular (LV) and right ventricular (RV) leads is performed, showing a persistent delay in the anterolateral and posterolateral wall. By anticipating stimulus of LV lead of 20 milliseconds (B), delay is reduced and dyssynchrony (by Systolic Dyssynchrony Index [SDI]) and systolic function (by ejection fraction [EF]) improve, but still there is a little delay in anterolateral basal segment. Further anticipation of LV lead stimulus (C) leads to disappearance of lateral delay but an apical delay emerges and indexes of systolic function and dyssynchrony worsen.](image)
Imaging

Conclusion
Realtime 3D echocardiography allows accurate measurement of LV size, function and dyssynchrony to be performed; it measures all 16 myocardial segments in one single acquisition, allowing for a rapid assessment of the area of latest LV activation to guide optimal LV lead placement. It is a very promising technique, not only in predicting response to CRT but also in guiding VV optimisation. With single-beat acquisition, a nice analysis of left ventricle volumes, function and dyssynchrony can be performed, even in a condition of atrial fibrillation. Care must be taken to improve temporal resolution, but satisfactory volume rates can now be obtained by optimising the settings of the machine.